

Phone: 651/234-7388 Fax: 651/234-7370

Date: February 4, 2011

Hari Kalla Acting Director, Office of Transportation Operations Federal Highway Administration Office of Transportation Operations 1200 New Jersey Avenue, S.E., HOTO-1 Washington, DC 20590

RE: Request to Experiment – Converging Chevrons – St. Louis County, MN

Dear Mr. Kalla:

In accordance with the 2009 Manual on Uniform Traffic Control Devices (MUTCD), I am requesting permission to experiment with the above traffic control device. Under the authority of the MUTCD, the Minnesota Department of Transportation (Mn/DOT) has authorized and published a Minnesota version of this manual (MN MUTCD). The current MN MUTCD edition is dated July, 2005.

St. Louis County did a corridor safety analysis on Midway Road from U.S. Hwy 2 to Trunk Highway (T.H.) 194 in 2010. The intersection at Maple Grove Road (CSAH 6) and Midway Road had the highest weighted severity index. As a result of this study and in conjunction with a programmed pavement rehabilitation project, the County plans to implement two experimental safety measures at this intersection to reduce the speeds of vehicles approaching this intersection on Midway Road– narrow lanes and converging chevrons.

Enclosed is the County's description of their project that further details these traffic control devices and their plan for monitoring and evaluating the devices.

Thank you for your time and attention in regards to this request.

Sincerely,

anelle anderan

An Equal Opportunity Employer



Janelle Anderson, P.E. Tort Claims and Traffic Standards Engineer Office of Traffic, Safety, and Technology

Enclosures

CC:

Phil Forst – FHWA Minnesota Division James T. Foldesi, Public Works Director/Highway Engineer Will Stein – FHWA Ken Johnson – Mn/DOT

An Equal Opportunity Employer

FHWA Request to Experiment

Integrated Speed Reduction Treatment for Intersections (ISRTI)

Submitted by: St. Louis County Public Works Department

Date: 2/1/2011

1.0 Introduction

St. Louis County Public Works Department is scheduled to repave a segment of County State Aid Highway No. 13 (Midway Road), starting at U.S. Highway 2 and ending at State Trunk Highway 194 in 2011. Midway Road is located in the City of Hermantown. The City of Hermantown is located within the Duluth-Superior metropolitan area. In 2009, the estimated population of the City of Hermantown was 9,586 people¹. Midway Road is classified as a minor arterial. It serves as the primary route to connect Interstate 35 with the City of Hermantown and surrounding townships. Additionally, it also connects Interstate 35 with U.S. Highway 2 and U.S. Highway 53. The estimated 2011 AADT ranges from 8,800 vehicles per day in the south half of the segment to 7,000 vehicles per day in the north half of the segment². Midway Road is constructed as a rural section with 10 feet shoulders. Figure 1 displays a map of the segment of Midway Road planned for construction and the location of the proposed experiment. During the project planning, a review of intersection crashes for this corridor was performed to identify potential traffic safety countermeasures that could be implemented with the construction project.



Figure 1. Map of Project Area

^{1.} US Census Bureau. <u>http://www.census.gov/</u>. Accessed January 27, 2011.

Minnesota Department of Transportation – Traffic Volumes Map. <u>http://www.dot.state.mn.us/traffic/data/html/volumes.html</u>. Accessed January 27, 2011

2.0 Traffic Analysis

The initial crash analysis was completed for the 10 year period of 2000 to 2009. Table 1 displays intersection crashes by crash severity starting with U.S. Highway 2 and ending with State Trunk Highway 194 in order of south to north¹. It should be noted that the intersections of U.S. Highway 2 and State Trunk Highway 194 are controlled by a traffic signal. All other intersections on this segment are controlled by a two-way stop.

INTERSECTING	C	RAS	H SEV	/ERIT	Y	TOTAL	WEIGHTED
ROAD	К	А	В	С	Ν	TOTAL	INDEX ^A
U.S. 2			1	9	7	17	28
Hermantown Rd.	1			2	3	6	12
Maple Grove Rd.		2	3	9	21	35	56
Jamebard Rd.			1			1	3
West Arrowhead Rd.			1	4	6	11	17
Hagberg Rd.					2	2	2
Rose Rd.			1	1		2	5
STH 194			5	7	11	23	40

Table 1, 2000 to	2009 Midway	Rd. Intersection	Crash Summary
1 4010 11 2000 00	a cost in the training	itu, intersection	Crush Summary

A. See Appendix for calculation of the Weighted Severity Index.

The intersection of Midway Road and County State Aid Highway No. 6 (Maple Grove Road) experienced the highest number of crashes for the analysis period. Additionally, this intersection also experienced the highest Weighted Severity Index. This suggests that relative to the number of crashes experienced by an intersection on this corridor, the intersection of Midway Road and Maple Grove Road experienced a larger number of more severe crashes than all other intersections. Therefore, the intersection of Midway Road and Maple Grove Road was identified as a candidate to implement some type of traffic safety countermeasure.

The second phase of the crash analysis was to identify the predominant crash diagram. Figure 2 displays the chart of crashes by crash diagram that occurred at the intersection of Midway Road and Maple Grove Road for the same 10 year period of 2000 to 2009. As indicated by the chart, the predominant crash diagram is right-angle crashes. A collision diagram was also completed to identify the pattern of the right-angle crashes within the intersection. A copy of the collision diagram is included in the Appendix.

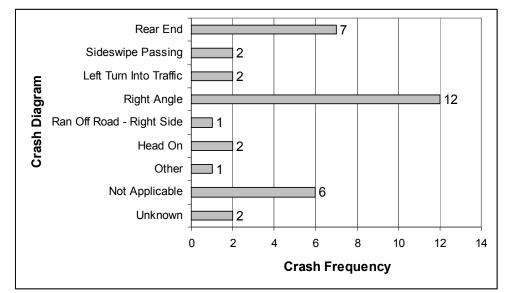


Figure 2. 2000 to 2009 Midway Rd. and Maple Grove Rd. Intersection Crashes by Crash Diagram

A turning movement count was performed at this intersection on April 8, 2010. A summary of the peak hour turning movement count is included in the Appendix. During the peak hour, there is a significant left turning movement from the east approach of Maple Grove Road. Due to the heavy traffic volume on Midway Road, the east approach of Maple Grove Road is currently experiencing an average delay of 26.5 seconds per vehicle which corresponds to a level of service D. See the Appendix for the Synchro report. A traffic signal warrant analysis was completed using the data from the 2010 turning movement count. For the year 2010, no traffic signal warrants were satisfied. For that year, Warrant 1A (Eight Hour Vehicular Volume -Minimum Volume) satisfied six of the eight hours required. Warrant 2 (Four Hour Vehicular Volume) satisfied three of the four hours required. A sensitivity analysis was performed to determine what year a traffic signal may be warranted using a twenty year growth factor of 1.2. From this analysis, 2018 was the first year that a warrant, Warrant 1A, was satisfied. In the year 2020, Warrant 1A, Warrant 2 and Warrant 3 (Peak Hour Volume) were satisfied. This suggests there may be a 10 to 15 year window before a traffic signal or other traffic control device is seriously considered. In the meantime, engineering judgment supports implementing a traffic safety countermeasure until a change in traffic control is completed.

Figure 3 displays the existing intersection lane configuration.

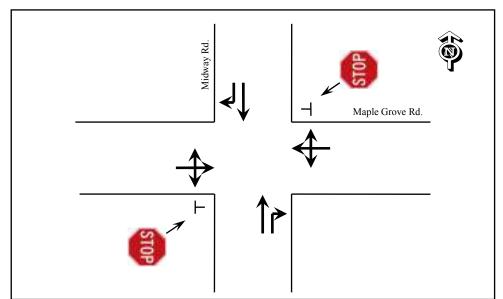


Figure 3. Midway Rd. and Maple Grove Rd. Intersection Lane Configuration

3.0 Proposed Experimental Improvement

St. Louis County researched potential improvements to reduce right-angle crashes. Two concepts were identified that by combining together have great potential to improve the intersection safety performance. The first concept is to implement lane narrowing on both major approaches. The second concept is to install converging chevrons within the traveled lanes on both major approaches. The following sections discuss each of these concepts and their observed performance.

3.1 Lane Narrowing Concept

At rural two-way stop controlled intersections, drivers stopped on the minor approach must be able to accurately estimate the available gap in the traffic stream on the major approaches. One of the contributing factors to right-angle crashes is due to the inability of a driver stopped on the minor approach to accurately estimate this gap. In this case, a driver on the minor approach may underestimate the "actual" gap and thereby select an insufficient gap to safely perform a turning maneuver resulting in a right-angle crash. Reducing vehicle speeds on the major approaches to an intersection has been identified as a strategy to improve intersection safety¹.

The first concept implements lane narrowing on both major approaches of an intersection. The standard lane width for a major County State Aid Highway is 12 feet. This concept reduces the lane width to nine or ten feet before the intersection. The objective of this concept is to reduce the speed of vehicles approaching the intersection on the major approaches. To enforce the narrow lane, this concept includes rumble strips in the center median and along the edgeline².

^{1.} NCHRP Report 500, Volume 5: A Guide for Addressing Unsignalized Intersection Collisions. 2003. Transportation Research Board. Washington, D.C.

Hughes W., Jagannathan R., Gross, F. 2008. Two Low-Cost Safety Concepts for Two-Way STOP-Controlled, Rural Intersections on High-Speed Two-Lane, Two-Way Roadways. Federal Highway Administration. Publication No. FHWA-HRT-08-063.

In a research project in Iowa, an experimental traffic calming treatment reduced lane widths to 10.0 feet to 10.5 feet with the objective to reduce vehicle speeds¹. Figure 4 displays a schematic of the lane narrowing concept².

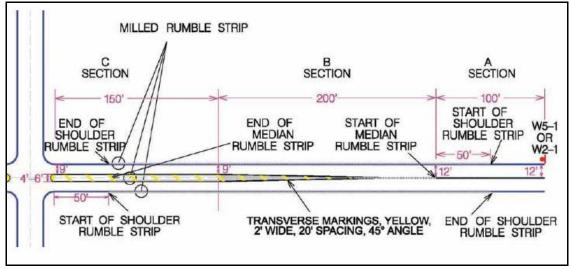


Figure 4. Lane Narrowing Concept Schematic

It was reported that after the implementation of the lane narrowing concept in nine locations in Pennsylvania, Kentucky, Missouri and Florida, there was an average reduction in vehicle speeds of 3.5 mph across all locations. The average reduction in the 85th percentile vehicle speeds was 4.5 mph across all locations. The crash analysis found an average reduction in the crash rates of 31 percent for total crashes, 20 percent for fatal and major injury crashes, and 42 percent of right-angle crashes. However, there was an average increase in the crash rate for rear-end crashes of 54 percent. It was hypothesized that speed differential, and turning and passing vehicles were the reasons for this increase in rear-end crashes. Finally, a statistical hypothesis test was performed on the total, and fatal and major injury crash rates for all locations included in the study. For the 95 percent confidence level, the reduction in total crash rate was not significant. However, at the same confidence level, there was a significant reduction in fatal and injury crashes².

As with any countermeasure, there will generally be some type of side effect. However, the goal of the practitioner is to balance those side effects with the benefits. In the case of the lane narrowing concept, there was a reduction in the right-angle crash rate by 42 percent and a statistically significant reduction in fatal and injury crashes. It should be noted that right-angle crashes generally result in higher severity crashes than rear-end crashes. And in the case of the intersection of Midway Road and Maple Grove Road, right-angle crashes were the dominate crash diagram.

^{1.} Hallmark S. et. al. 2007. *Evaluation of Gateway and Low-Cost Traffic-Calming Treatments for Major Routes in Small Rural Communities*. Center for Transportation Research and Education. Iowa State University.

Hughes W., Jagannathan R., Gross, F. 2008. Two Low-Cost Safety Concepts for Two-Way STOP-Controlled, Rural Intersections on High-Speed Two-Lane, Two-Way Roadways. Federal Highway Administration. Publication No. FHWA-HRT-08-063.

3.2 Converging Chevron Pattern Concept

The second concept is a converging chevron pattern. Figure 5 displays the schematic of the converging chevron pattern concept¹. The key design of converging chevrons progressively decreases the distance between the chevrons and reduces the width of successive chevrons. When a driver traverses the converging chevron pattern, the design of the converging chevrons creates an illusion for the driver that the vehicle is traveling faster than it really is. As a result, drivers will tend to slow down their vehicle. A research project in Iowa installed converging chevron pattern was designed to reduce vehicle speeds from 35 mph to 25 mph. The average speed reduction achieved over a 12 month period ranged from 0.4 mph to 1.3 mph for one location and 0.7 mph to 3.0 mph for another location. In many cases, the speed reductions were statistically significant at the 95 percent confidence level¹.

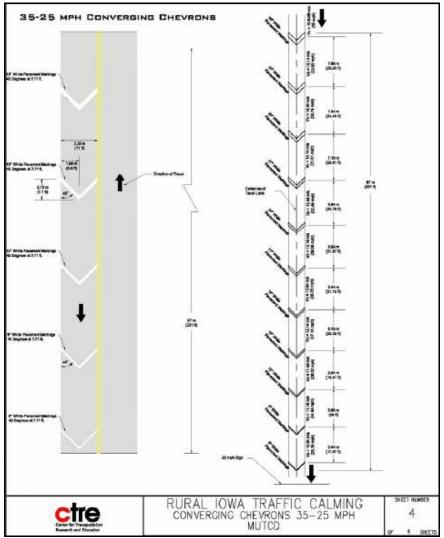


Figure 5. Converging Chevron Pattern Concept Schematic

^{1.} Hallmark S. et. al. 2007. *Evaluation of Gateway and Low-Cost Traffic-Calming Treatments for Major Routes in Small Rural Communities*. Center for Transportation Research and Education. Iowa State University.

A research project in Minnesota also installed a converging chevron pattern and found a reduction in average vehicle speeds over a four year period of 1 mph to 6 mph for two directions of traffic. The 85th percentile speed for the same time period and travel directions was reduced by 1 mph to 7 mph¹.

4.0 St. Louis County Experimental Concept

St. Louis County proposes to implement an Integrated Speed Reduction Treatment for Intersections (ISRTI) by integrating the lane narrowing concept with the converging chevron pattern concept. One difference is that St. Louis County will not include rumble strips to enforce the narrow lanes due to noise concerns. It is hypothesized that incorporating the converging chevrons will enhance the speed reduction effect of the narrow lanes. The combined effects of the lane narrowing and converging chevron pattern is expected to effect, at a minimum, the same speed reduction benefit as the lane narrowing concept with the rumble strips. See the Appendix for the layout of the ISRTI at the intersection of Midway Road and Maple Grove Road.

4.1 St. Louis County Experimental Concept Design

The ISRTI will narrow both major approach lanes from 12 feet to 10.5 feet and place converging chevrons within the lane. The narrow lanes will result in a three feet wide median. The most complex aspect of creating this design was designing the converging chevrons. A method is available to determine the design parameters of the converging chevron pattern. This method was used to design the converging chevron pattern in Milwaukee, Wisconsin².

This method requires the determination of five variables to design the converging chevron pattern. The first and second variables are the design speed entering the converging chevron pattern and the design speed exiting the converging chevron pattern. St. Louis County designed the converging chevron pattern to reduce the speed of a vehicle from 55 mph to 45 mph. The third variable was to estimate a deceleration value due to braking. An initial effort to estimate deceleration with no braking was performed by driving a passenger vehicle at 55 mph and allowing the vehicle to decelerate by coasting (no brakes applied) to 45 mph over level terrain. For ten trial runs, the average time to decelerate was 12.3 seconds. The deceleration was then calculated to be 1.20 ft/sec². A deceleration due to braking of 3.30 ft/sec² was used for the Milwaukee design². This deceleration value appeared to be too aggressive. Given the deceleration value of 1.20 ft/sec² due to coasting, the deceleration value of 2.50 ft/sec² was selected as a "best guess" given the relative benchmarks. The fourth variable was to identify the reaction time of a driver. The Milwaukee design used a reaction time of 0.5 seconds. This value appeared reasonable so it was used in this St. Louis County design. The fifth variable was to estimate the number of chevrons per second a vehicle would cross. The Milwaukee design used 2.2 chevrons/sec. Because there were no other reference points available in the literature search, this value was assumed reasonable and used in the St. Louis County design. See the Appendix for a detail of the design calculations.

^{1.} Corkle J., Giese J. and Marti M. 2001. *Investigating the Effectiveness of Traffic Calming Strategies on Driver Behavior, Traffic Flow, and Speed*. Minnesota Local Road Research Board. Minnesota Department of Transportation.

^{2.} Drakopoulos, A., Vergou, G. 2003. *Evaluation of the Converging Chevron Pavement Marking Pattern at one Wisconsin Location*. AAA Foundation for Traffic Safety.

The first calculation was to determine the length of the converging chevron pattern which was calculated as 472.6 feet. The second calculation was to determine the total time for a vehicle to travel the design length which was calculated as 6.50 seconds. The third calculation was to determine the total number of chevrons required. The number of chevrons required for each direction was calculated as 15 chevrons with 14 spaces. From these design parameters, the design velocity, distance and location could then be calculated. Table 2 displays these design parameters of the converging chevron pattern. Chevron 1 is the first chevron a vehicle crosses when approaching the intersection whereas Chevron 15 is the last chevron a vehicle crosses before entering the intersection. The velocity is the design velocity a vehicle will be traveling at immediately after crossing the respective chevron. For example, immediately upon crossing Chevron 5, the design velocity of a vehicle will be 77.37 ft/sec, or 52.6 mph. The distance between the chevrons will progressively decrease from 40.4 feet when a vehicle first enters the converging chevron pattern to 30.8 feet. There will be a distance of 60 feet between Chevron 15 and the near side edgeline of Maple Grove Road. The width of the chevrons will start at 32 inches and decrease at a rate of 2 inches per chevron to a width of 4 inches.

-	Chevron	Velocity (ft/sec)	Distance (ft)	Location (ft)	Width (in)		
	Chevron 1	80.85	40.4	543	32		
	Chevron 2	80.85	37.3	503	30		
	Chevron 3	79.69	36.7	465	28		
_	Chevron 4	78.53	36.2	429	26		
Travel	Chevron 5	77.37	35.6	392	24		
Ira	Chevron 6	76.21	35.1	357	22		
of	Chevron 7	75.05	34.6	322	20		
ON	Chevron 8	73.89	34.0	287	18		
Direction	Chevron 9	72.73	33.5	253	16		
<u> </u>	Chevron 10	71.57	32.9	220	14		
	Chevron 11	70.41	32.4	187	12		
	Chevron 12	69.25	31.9	154	10		
	Chevron 13	68.09	31.3	122	8		
	Chevron 14	66.92	30.8	91	6		
- ↓	Chevron 15	65.76	30.3	60	4		
·	Intersect	tion Offset		30			

Table 2. C	onverging Cl	nevron Design	Parameters
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4.2 St. Louis County Experimental Concept Expected Performance

As discussed in Section 3.1, the lane narrowing concept resulted in an average reduction of vehicle speeds of 3.5 mph. From Section 3.2, the converging chevron pattern appeared to result in a general reduction of vehicle speeds of 1 mph to 5 mph. It is unclear what effect the combination of lane narrowing and converging chevrons have on effect speed reduction. Based upon engineering judgment, it is assumed the ISRTI will effect a sustained reduction in vehicle speeds of 5 mph.

An estimate of the increase in gap time was then determined based upon this estimated reduction in vehicle speeds. Prior to the turning movement count, traffic counters were placed on Midway Road to determine the peak day to perform the turning movement count. This initial traffic count also provided average speed and average headway information. Using the relationship between flow, speed and density, the estimated increase in gap time could be determined. Two random 15 minute time periods were selected from the initial traffic count to be used as case studies. For the first case, there was a volume of 305 vehicles with an average speed of 41 mph and average headway of 2.94 seconds. In the second case, there was a volume of 121 vehicles and an average speed of 44 mph and average headway of 7.38 seconds. Using the estimated speed reduction of 5 mph, the average headway, or gap time, was increased in the first case by 0.41 seconds and in the second case by 0.93 seconds. See the Appendix for a detail of the gap calculations. As demonstrated by these two cases, the ISRTI is expected to increase gap time and therefore reduce the risk of a crash.

A benefit/cost analysis was completed to determine if the potential increase in rear-end crashes outweighs the benefit of reduced right-angle crashes. Utilizing the average reduction in the right-angle crash rate of 42 percent and an increase in the rear-end crash rate of 54 percent as crash reduction factors, the benefit/cost ratio was computed as 6.14. See the Appendix for a detail of benefit/cost analysis. It appears that ISRTI will have a significant overall safety benefit even with the potential increase in rear-end crashes.

Finally, a review of practical advantages and disadvantages of the ISRTI was completed. Some advantages identified were its low cost (estimated cost is \$25,000), it is non-invasive to vehicles or nearby residents (no bumps therefore no noise), and roadway geometrics are not altered. Some disadvantages identified were the inability to view the pavement markings during winter due to snow cover, and that the pavement markings are subject to high-wear due to winter maintenance activities. To reduce wear, St. Louis County will utilize ground-in pavement markings.

5.0 Patent/Copyright Statement

St. Louis County is not aware of any pending or current patents or copyrights on either the lane narrowing concept or converging chevron pattern concept.

6.0 Evaluation Plan

St. Louis County will commit to performing an evaluation of the ISRTI at one year, two years and three years from implementation. This evaluation will include a "before and after" study utilizing crash and speed data. The crash analysis will include a comparison of total crashes, fatal and injury crashes, right-angle crashes and rear-end crashes. The speed analysis will include a comparison of vehicle speeds on the major approaches entering and leaving the pattern. Speed measurements will be performed immediately (days), one month, three month, six month, one year, two years and three years from implementation. The speed measurements are dependant upon weather conditions. If there is snow covering the roadway, the traffic counters cannot be deployed and vehicle speeds will not be normal due to winter weather conditions. Of interest to St. Louis County is whether a driver adaptation effect will be observed in which drivers return to "normal" driving behavior over time as indicated by comparable speeds to the before period. The intent to restore the experimental site will be dependant upon the findings from the evaluation reports. If the evaluation reports suggest an improvement in traffic safety, St. Louis County will continue to maintain the ISRTI perpetually into the future. If safety concerns directly or indirectly related to the ISRTI are identified, or a different traffic control device such as a traffic signal is installed, St. Louis County will restore the intersection to a condition that complies with the Manual on Uniform Traffic Control Devices (MUTCD). St. Louis County recognizes that the Federal Highway Administration has the authority to terminate this experimental application at anytime and will hereby comply with any such order.

7.0 Conclusion

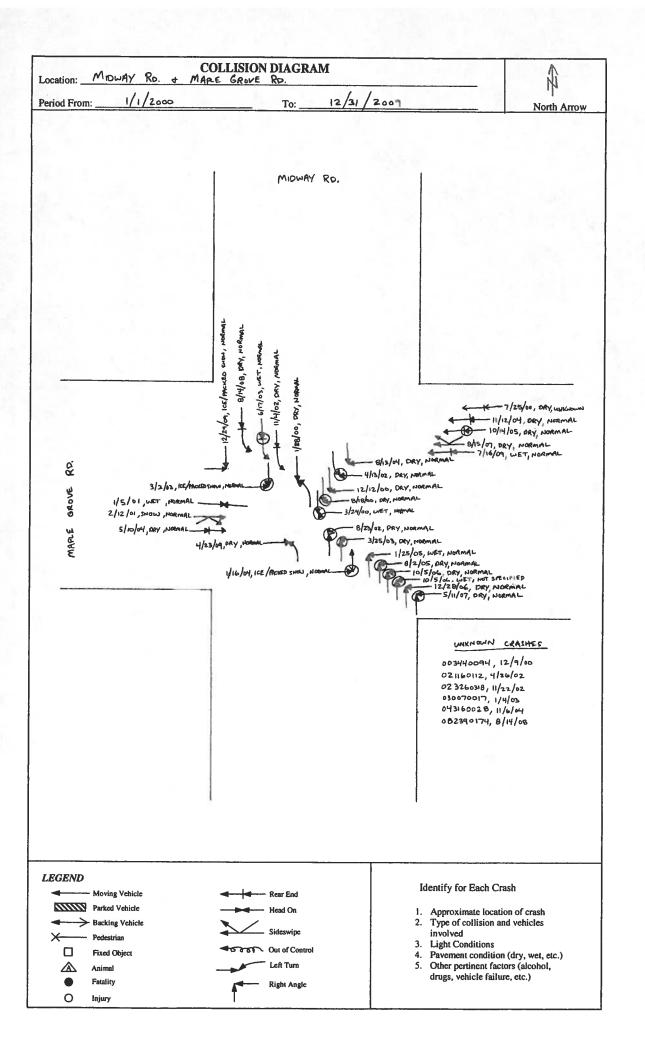
St. Louis County believes ISRTI has the potential to significantly improve traffic safety at rural two-lane, high speed intersections. If positive findings are documented from this experiment, St. Louis County would urge the Federal Highway Administration and Minnesota Department of Transportation to consider further evaluation of this concept with the intent of identifying it as an approved strategy in the MUTCD.

APPENDIX

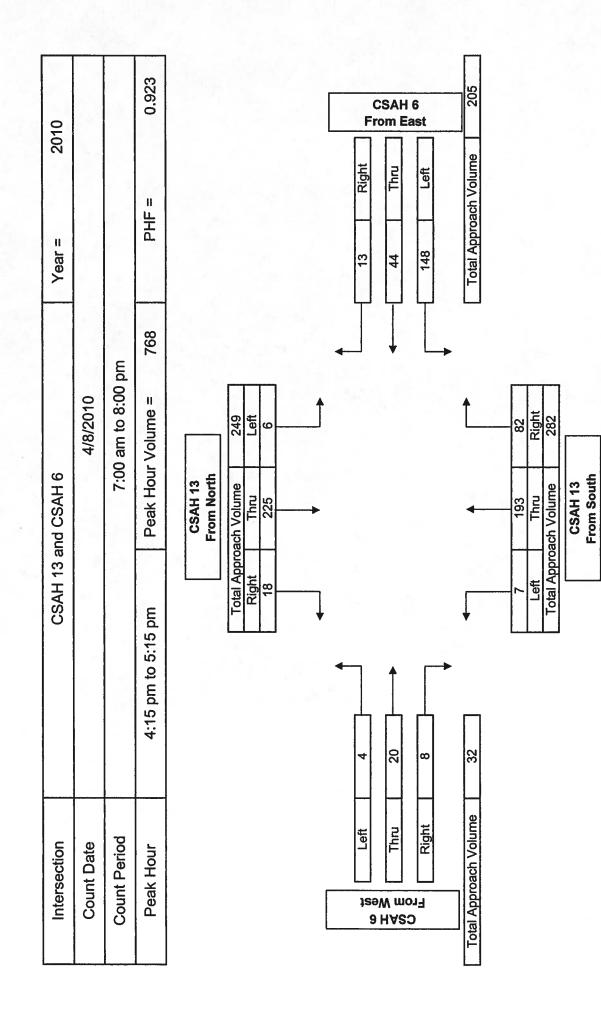
WEIGHTED SEVERITY INDEX

Weighted Severity Index = $(K \times 5) + (A \times 4) + (B \times 3) + (C \times 2) + N$

COLLISION DIAGRAM



PEAK HOUR TURNING MOVEMENT COUNT



SYNCHRO REPORT

HCM Unsignalized Intersection Capacity Analysis 3: Int

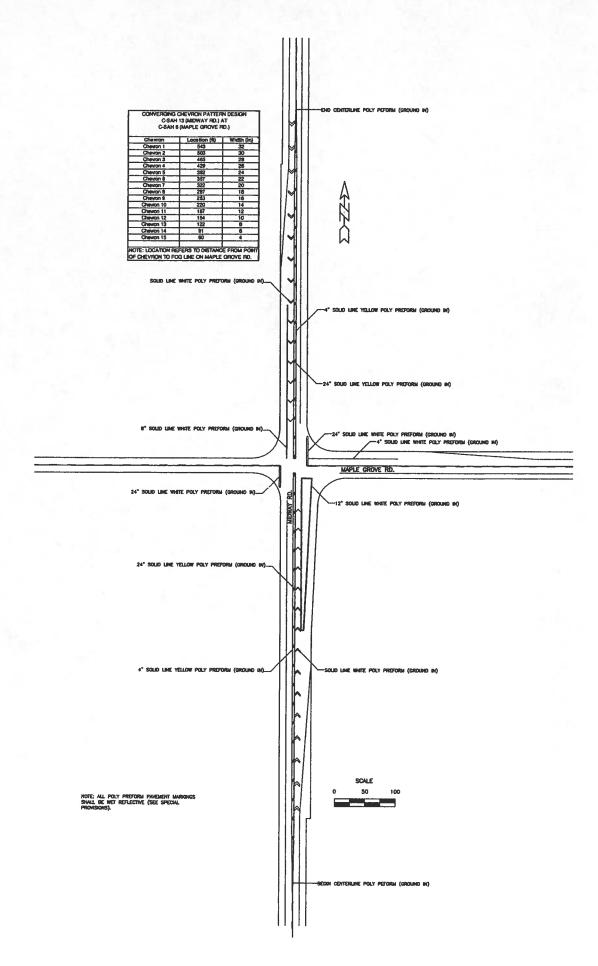
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Movement	EBL	EBT	EBR	WBL	WBT	WBR	NBL	NBT	NBR	SBL	SBT	SBR
Lane Configurations		ф			4			4	7		र्भ	7
Sign Control		Stop			Stop			Free			Free	
Grade		0%			0%			0%			0%	
Volume (veh/h)	4	20	8	148	44	13	7	193	82	6	225	18
Peak Hour Factor	0.33	0.63	0.50	0.88	0.79	0.54	0.44	0.79	0.79	0.38	0.92	0.64
Hourly flow rate (veh/h)	12	32	16	168	56	24	16	244	104	16	245	28
Pedestrians												
Lane Width (ft)												
Walking Speed (ft/s)												
Percent Blockage												
Right turn flare (veh)												
Median type		None			None							
Median storage veh)												
vC, conflicting volume	604	656	245	584	580	244	273			348		
vC1, stage 1 conf vol												
vC2, stage 2 conf vol												
tC, single (s)	7.1	6.5	6.2	7.1	6.5	6.2	4.1			4.1		
tC, 2 stage (s)												
tF (s)	3.5	4.0	3.3	3.5	4.0	3.3	2.2			2.2		
p0 queue free %	97	92	98	56	87	97	99			99		
cM capacity (veh/h)	350	375	794	380	415	794	1291			1211		
Direction, Lane #	EB 1	WB1	NB 1	NB 2	SB 1	SB 2	E PARSE	ferla di	Hull Strip		(10) jet	-12-12-12-12-
Volume Total	60	248	260	104	260	28			Grees		1.1	100
Volume Left	12	168	16	0	16	0						
Volume Right	16	24	0	104	0	28						
cSH	430	409	1291	1700	1211	1700						
Volume to Capacity	0.14	0.61	0.01	0.06	0.01	0.02						
Queue Length (ft)	12	97	1	0	1	0						
Control Delay (s)	14.7	26.5	0.6	0.0	0.6	0.0						
Lane LOS	В	D	А		А							
Approach Delay (s)	14.7	26.5	0.4		0.5							
Approach LOS	В	D										
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Intersection Summary Average Delay Intersection Capacity Ut	ilization	resolution Production	8.1 44.5%	l.	CU Leve	el of Ser	vice		A	and		

EAST APPROACH DELAY = 26.5 sec LOS = D

Baseline

INTEGRATED SPEED REDUCTION TREATEMENT FOR INTERSECTIONS

"LAYOUT"



7:\Project F es\2011 OVER!AYS\midway_map a grave.dwg, 11/23/2010 2:51:42 PV

INTEGRATED SPEED REDUCTION TREATEMENT FOR INTERSECTIONS

"DESIGN CALCULATIONS"

Direction of Traffic

V _o	55	mi/hr 🔶	80.85	ft/sec
V ₁	45	mi/hr 🔶	66.15	ft/sec
а	-2.50	ft/sec ²		No File
$-t_r$	0.5	sec		
Rate	- 2.2	chev/sec		
L	472.6	ft		
t total	6.50	Sec	1. 2. 16 1. 1	
Chev #	15			
Spaces	14			

INSTRUCTIONS

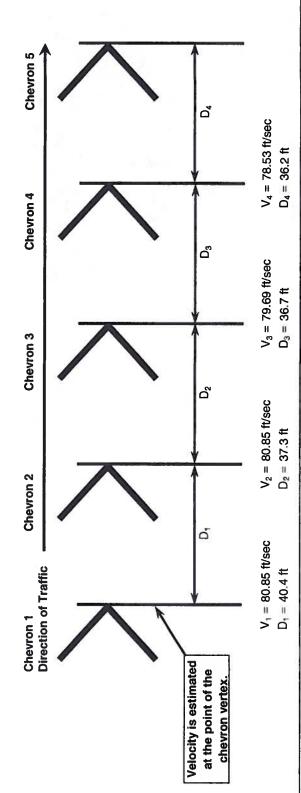
ONLY ENTER VARIABLES INTO THE YELLOW CELLS.

Identify the speed entering the chevron pattern (v_o) and the speed exiting the chevron pattern (v_f) .

Estimate the deceleration rate (a).

Reaction time (t_r) and Rate are assumed from the literature.

Chevron	Velocity (ft/sec)	Distance (ft)	Location (ft)	Width (in)
Chevron 1	80.85	40.4	543	32
Chevron 2	80.85	37.3	503	30
Chevron 3	79.69	36.7	465	28
Chevron 4	78.53	36.2	429	26
Chevron 5	77.37	35.6	392	24
Chevron 6	76.21	35.1	357	22
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Chevron 13	68.09	31.3	122	8
Chevron 14	66.92	30.8	91	6
Chevron 15	65.76	30.3	60	4
				_
Interse	ction Offset		30	



time, t_r. It is assumed there will be no reduction in speed over this distance. Therefore D₁ is computed by V₁ *t_r where V₁ is the speed before entering the chevron It is assumed upon crossing the first chevron, a driver will only perceive the chevron pattern at this point. The time to travel distance D₁ is identified as the reaction pattern.

estimated velocity, V_3 at Chevron 3 is calculated using the equation $v_f = v_o + at$ where v_f is equal to V_3 , v_o is equal to V_2 , a is the deceleration constant and t is pattern, trate by the total number of spaces in the chevron pattern. It is assumed a vehicle will experience uniform deceleration over the entire chevron pattern. The Because there is assumed to be no speed reduction between Chevron 1 and Chevron 2, V_2 is equal to V_1 . The distance, D_2 is calculated using the equation d = $v_ot + 1/2at^2$ where v_o is equal to V_2 , a is the decleration constant and t is calculated by dividing the time to travel the distance of the total length of the chevron calculated the same as used in the equation for D_2 . The remaining distance and velocity values of the chevron pattern are computed the same as D_2 and V_3 . Velocity Calculation

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-	V.o	55	55 mi/hr 🔶	80.85	80.85 ft/sec		Chevron	Velocity (ft/sec)	Distance (ft)	Location (ft)	Width (in)
2	1¢	45	45 mi/hr 🎔	66.15	66.15 ft/sec		Chevron 1	80.85	40.4	543	32
ო	e	-2.50	-2.50 ft/sec ²				Chevron 2	80.85	37.3	503	30
4	tr	9.6	0.5 sec			Dire	Chevron 3	[36.7	465	28
ŝ	Rate	2.2	2.2 chev/sec	11 M		ecti	Chevron 4	=IF(G5=0,0,H4+(;	36.2	429	26
9	L L	472.6 ft	Æ			on	Chevron 5	77.37	35.6	392	24
2	t total	6.50	6.50 sec			of T	Chevron 6	76.21	35.1	357	22
8	Chev #	15				raf	Chevron 7	75.05	34.6	322	20
თ	Spaces	14				lic	Chevron 8	73.89	34.0	287	18
10		INS	INSTRUCTIONS	SNC			Chevron 9	72.73	33.5	253	16
11		41.97				->	Chevron 10	71.57	32.9	220	14
12	ONLY E	NTERV	ONLY ENTER VARIABLES INTO THE	OINI SE	THE	>	Chevron 11	70.41	32.4	187	12
13	VELLO	VELLOW CELLS.	Š.				Chevron 12	69.25	31.9	154	10
14							Chevron 13	68.09	31.3	122	8
15		he speed	Identify the speed entering the chevron pattern	e chevron	n pattern		Chevron 14	66.92	30.8	91	9
16	(v_o) and the	he speed	(v_o) and the speed exiting the chevron pattern	chevron	pattern		Chevron 15	65.76	30.3	60	4
17	(A)										
18	Fchimate	the decel	F stimate the deceleration rate (g)								
19											
20	Reaction	time (t_r)	Reaction time (t_r) and Rate are assumed from	e assume	dfrom						
: 6	the literature.	mre.			8						
Ľ											

Distance Calculation

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	A	•	U	0	ш	L	S	H	1	ſ	¥
-	Vo	55	mi/hr →	80.85	80.85 ft/sec		Chevron	Velocity (ft/sec)	Distance (ft)	Location (ft)	Width (in)
2	Vf	45	45 mi/hr 🔰	66.15	66.15 ft/sec		Chevron 1	80.85	40.4	543	32
e	ß	-2.50	-2.50 ft/sec ²				Chevron 2	80.85	37.3	503	30
4	tr	0.5	0.5 sec			Dire	Chevron 3	79.69	36.7	465	28
5	Rate	2.2	2.2 chev/sec			ecti	Chevron 4	78.53	=IF(G5=0,0,(H5*(429	26
9	T	472.6 ft	ft			on	Chevron 5	77.37	35.6	392	24
2	f total	6.50	6.50 sec			of T	Chevron 6	76.21	35.1	357	22
8	Chev #	15				rafi	Chevron 7	75.05	34.6	322	20
6	Spaces	14				lic	Chevron 8	73.89	34.0	287	18
10		SNI	INSTRUCTIONS	SNC			Chevron 9	72.73	33.5	253	16
11						>	Chevron 10	71.57	32.9	220	14
12		NTERV	ONLY ENTER VARIABLES INTO THE	ES INTO	THE		Chevron 11	70.41	32.4	187	12
13	-	VELLOW CELLS.	S.				Chevron 12	69.25	31.9	154	10
14							Chevron 13	68.09	31.3	122	8
15		he speed (Identify the speed entering the chevron pattern	e chevron	pattern		Chevron 14	66.92	30.8	91	9
16		he speed ((v_o) and the speed exiting the chevron pattern (v_b)	chevron	pattern		Chevron 15	65.76	30.3	60	4
- 9		810 810		8							
19		the decel	Estimate the deceleration rate (a) .	e (a).							
21 21	the part of the	time (t _r) a ture.	Reaction time (t_r) and Rate are assumed from the literature.	re assum e	dfrom						
3 8											

Location Calculation

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-	V.o	55	55 mi/hr 🔶	80.85 ft/sec			Chevron	Velocity (ft/sec)	Distance (ft)	Location (ft)	Width (in)
2	Νŝ	45	45 mi/hr 🎔	66.15 ft/sec			Chevron 1	80.85	40.4	543	32
ო	a	-2.50	-2.50 ft/sec ²				Chevron 2	80.85	37.3	503	30
4	tr	0.5	0.5 sec		Dire		Chevron 3	69'62	36.7	465	28
5	Rate	2.2	2.2 chev/sec		ecti		Chevron 4	78.53	36.2	=16+15	26
9	7	472.6 ft	Ĥ		on		Chevron 5	77.37	35.6	392	24
2	t total	6.50 sec	sec		of 1		Chevron 6	76.21	35.1	357	22
œ	Chev #	15			rafi		Chevron 7	75.05	34.6	322	20
თ	Spaces	14			fic		Chevron 8	73.89	34.0	287	18
10		SNI	INSTRUCTIONS	SNO	Γ	-	Chevron 9	72.73	33.5	253	16
Ŧ		2.11		2 10		\rightarrow	Chevron 10	71.57	32.9	220	14
12		NTERV	ARIABLE	ONLY ENTER VARIABLES INTO THE		>	Chevron 11	70.41	32.4	187	12
13	VELLO.	VELLOW CELLS.	S.				Chevron 12	69.25	31.9	154	10
14							Chevron 13	68.09	31.3	122	œ
15		he speed (entering th	Identify the speed entering the chevron pattern	a		Chevron 14	66.92	30.8	91	9
16		he speed (exiting the	(v_o) and the speed exiting the chevron pattern			Chevron 15	65.76	30.3	60	4
17	(h).										
18		the decale	antion anto								
19	Esumate	me nerei		c (a).							
20		time (t) a	nd Rate ar	Reaction time (t_{-}) and Rate are assumed from							ž
21		hure.									
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Width Calculation

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-	Vo	55	55 mi/hr 🔶	80.85	80.85 ft/sec		Chevron	Velocity (ft/sec)	Distance (ft)	Location (ft)	Width (in)
2	V.S	45	45 mi/hr 🎔	66.15	66.15 ft/sec		Chevron 1	80.85	40.4	543	32
ო	a	-2.50	-2.50 ft/sec ²				Chevron 2	80.85	37.3	503	30
4	tr	9-0	0.5 sec			Dire	Chevron 3	79.69	36.7	465	28
5	Rate	2.2	2.2 chev/sec			ecti	Chevron 4	78.53	36.2	429	=K6+2
9	T	472.6 ft	Ĥ			on	Chevron 5	77.37	35.6	392 I	24
2	f total	6.50	6.50 sec			of T	Chevron 6	76.21	35.1	357	22
8	Chev #	15				rafi	Chevron 7	75.05	34.6	322	20
6	Spaces	14				lic	Chevron 8	73.89	34.0	287	18
10		SNI	INSTRUCTIONS	SNC			Chevron 9	72.73	33.5	253	16
1						>	Chevron 10	71.57	32.9	220	14
12		INTERV	ONLY ENTER VARIABLES INTO THE	OTNI SE	THE		Chevron 11	70.41	32.4	187	12
13	VELLON	VELLOW CELLS.	Ś				Chevron 12	69.25	31.9	154	10
14							Chevron 13	68.09	31.3	122	60
15	Identify t	he speed	Identify the speed entering the chevron pattern	e chevror	n pattern		Chevron 14	66.92	30.8	91	6
16	(v_o) and the	he speed	(v_o) and the speed exiting the chevron pattern	chevron	pattern		Chevron 15	65.76	30.3	60	4
17	(A)										
18	T chimate	the decel.	\mathbf{F} stimute the deceleration rate (σ)								
19											
20	Reaction	time (1) ;	Reaction time (t_{\cdot}) and Rate are assumed from	e assime	dfrom						
21	the literature	ture.							2		
22										,	

	Velocity of vehicle immediately bc	before entering the chevron nattern (initial velocity) A/sec		0.5 sec	2.2 chev/sec	472.6 ft	6.50 sec	15	14	INCTRICTIONS		ONLY ENTER VARIABLES INTO THE	CELLS.		Identify the speed entering the chevron pattern	(v _o) and the speed exiting the chevron pattern			Estimate the deceleration rate (a) .	Reaction time (+) and Rate are accumed from		
4	V.o	Vf	0	tr	Rate	7	t total	Chev #	Spaces			ONLY EN	VELLOW CELLS.		Identify the	(v_o) and the	(h).	5 	L sumate th	R aach on hi	the literature	
	-	2	m	4	5	9	1	8	6	10	11	12	13	14	12	16	17	18	19	20	21	22

	Valucity of vahicle immediately	upon leaving the chevron pattern ec	, ft/sec.		sec					CTIONS		ONLY ENTER VARIABLES INTO THE			Identify the speed entering the chevron pattern	(vo) and the speed exiting the chevron pattern			1 rate (<i>a</i>).	Reaction time (+) and Rate are accounted from		
В	Valueity of value	upon leaving t	(final velocity), ft/sec.	0.5 sec	2.2 chev/sec	472.6 ft	6.50 sec	15	14	INSTRUCTIONS		NTER VARIA	VELLOW CELLS.		le speed entenir	e speed exiting		•	E summate the deceleration rate (a).	and (+) and R	ווווב אין מווער אין מווער	
A	V.O.	Vf	e	tr	Rate	7	t total	Chev #	Spaces			ONLY EI	VELLOV		Identify th	(v_o) and th	(v).	- - -	L'sumate t	D and on t	the literature	1 111 11 11 11 11 11 11 11 11 11 11 11
	-	2	e	4	5	9	2	8	6	10	1	12	13	14	15	16	17	18	19	20	21	

Vf Activity Characterization Characterization a becreleration value of a vehicle slowing down through the firm WION fr betremined in the field by measuring the time for a passenger vehicle to decelerate by coasting from the initial velocity to the final velocity. I ran 10 coasting from the wron deceleration trans from 55 to 45 mph and found an average deceleration time of 12.3 seconds. From this time, wron deceleration was calculated as -1.20 ft/sec ³ . Chev # the deceleration was calculated as -1.20 ft/sec ³ . Wron on the wron form date as -1.20 ft/sec ³ . Spaces 14 n Chevron (Chevron deceleration was calculated as -1.20 ft/sec ³ . NonLY ENTER VARIABLES INTO THE n Chevron (Chevron deceleration was calculated as -1.20 ft/sec ³ . YELLLOW CELLS. 0NLY ENTER VARIABLES INTO THE Chevron (Chevron deceleration was calculated as -1.20 ft/sec ³ . YELLLOW CELLS. 0NLY ENTER VARIABLES INTO THE n Chevron (Chevron deceleration was calculated as -1.20 ft/sec ³ . YELLLOW CELLS. 0NLY ENTER VARIABLES INTO THE n Chevron (Chevron deceleration was calculated as -1.20 ft/sec ³ . YELLLOW CELLS. 0NLY ENTER VARIABLES INTO THE n Chevron (Chevron deceleration was calculated as -1.20 ft/sec ³ . YELLLOW CELLS. 0NLY enter (ft) and the speed exiting
acting from the a sting from the n 10 coasting nd found an nds. From this tin nds. From this tin
e time for a sting from the n 10 coasting nd found an nds. From this time, o ft/sec ² . O ft/sec ² . Che
sting from the n 10 coasting nd found an nds. From this time, 0 ft/sec ² . Che Che Che
o the final velocity. I ran 10 coasting als from 55 to 45 mph and found an ration time of 12.3 seconds. From this time, nwron nwas calculated as -1.20 ft/sec ² . Chevron BLES INTO THE BLES INTO THE Chevron g the chevron pattern the chevron pattern the chevron pattern the chevron pattern e are assumed from
nds. From this time, 0 ft/sec ² . Che Che Che
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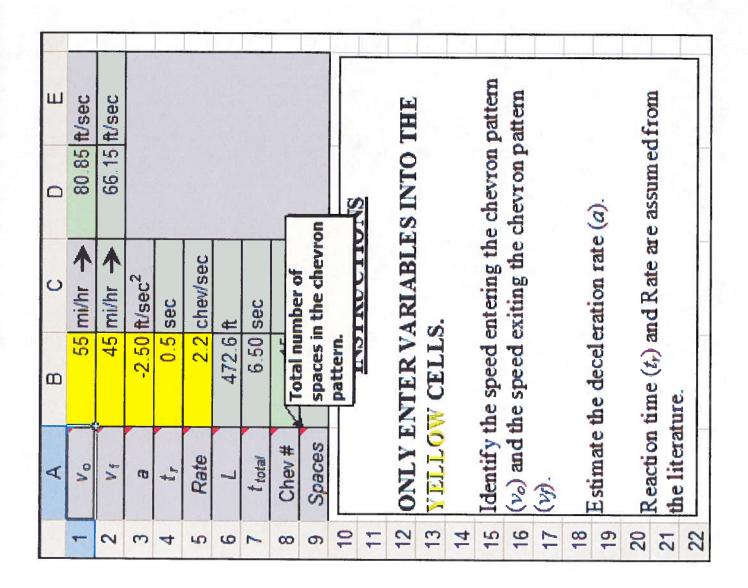
D	80.85 ft/sec	66.15 ft/sec	Time for a driver to react to the) NIC	CNT	ONLY ENTER VARIABLES INTO THE			Identify the speed entering the chevron pattern	(v _o) and the speed exiting the chevron pattern			(a).	Reaction time (1) and Rate are accumed from			
v	mi/hr 🔸	mi/hr 🔸	a. 2 a driver to	chevron pattern.	2.2 chev/sec	ŧ	sec			TDUCT	CUNTER TO AN I GUT	ARIABLE	th		entering th	exiting the			E summate the deceleration rate (a).	nd R ata ar			
Ð	55	45	Time for	chevron	2.2	472.6 ft	6.50	15	14	INC	21	NTERV	VELLOW CELLS.		he speed e	he speed e		•	the decele	time (+) a	mre (*r) a		
A	V.o	٧f	e	tr	Rate	L	t total	Chev #	Spaces			ONLY E	VELLO		Identify t	(v_o) and t	(A).	- F	Esumare	Reaction	the literature		
	1	2	e	4	2	9	2	8	6	10	1	12	13	44	15	16	17	18	19	20	21	22	00

	55 mi/hr → 80.85 ft/sec	45 mi/hr → 66.15 ft/sec	-2.50 ft/sec ²	The number of chevrons crossed hv a vehicle	per second. Assumed to be 2.2 chevrons/sec.	Ambandard Variation C 2002 Surface	the Converging Chevron Pavement Marking	Pattern at One Wisconsin Location. AAA	Foundation for Iraffic Safety.	INSTRUCTIONS		ONLY ENTER VARIABLES INTO THE	YELLOW CELLS.		Identify the speed entering the chevron pattern	(v _o) and the speed exiting the chevron pattern				Estimate the deceleration rate (a) .	Estimate the deceleration rate (a).
	_			Ż								Z	M		the	the			-	B	
A	Vo	Vf	Ð	tr	Rate	٢	t total	Chev #	Spaces			I VINO	VELLO		Identify	(v_o) and	(A).	F	H chimate		
1	+	2	3	4	5	9	1	8	6	10	11	12	13	4	12	16	17	18		6	

ш				Dire	ecti	on	of 1	raf	fic			١.,									
D	80.85 ft/sec	66.15 ft/sec			l is determined by the following equation:		[(e+2)/(;	Drakopoulos A., Vergou. G. 2003. Evaluation	on Pavement	Marking Partern at One Wisconsin Location. AAA Foundation for Traffic Safety.	NTO THE			evron pattern	vron pattern				and farm		
o	mi/hr 🄰	mi/hr 🔶	-2.50 ft/sec ²	sec	rmined by the f		$L = (v_o * t_r) + [(v_o^2 - v_r^2)/(2^*a)]$	ulos A., Vergou.	of the Converging Chevron Pavement	Marking Partern at One Wisconsin AAA Foundation for Traffic Safety.	ONLY ENTER VARIABLES INTO THE	Th.		Identify the speed entering the chevron pattern	(v_o) and the speed exiting the chevron pattern			Estimate the deceleration rate (a) .	Peach on time (+) and Date are accorded		
8	55	45	-2.50	0.5	L is defe		$r = (v_o^*)$	Drakopo	of the Co	AAA Four	NTERV	V CELLS		te speed e	ie speed e			the decele	ione (+) 2		
A	V.o	Vf	e	tr	Rate	1	t total	Chev #	Spaces		ONLYE	VELLOW CELLS.		Identify th	(v_o) and the	(M).	ŀ	Estimate	D and in the	the literature	
	-	2	9	4	5	9	1	8	6	10	12 =	13	14	15	16	17		19	20	21	5

U	Chev	Chevr	Chevr	Chevr	Chevr	M	NT O	M	VI	2	EE	T CITEVIN	Chevro	Chevro	Chevro						
L				Dire	ecti	01	llowing			for t.											
Ш	80.85 ft/sec	66.15 ft/sec				and farming and alaridans	the chevron pattern. Determined by the following			Known variables: d (i.e. L), v, and a. Solve for t.	e/(°,			Identify the speed entering the chevron pattern	(v _o) and the speed exiting the chevron pattern			(a)-	Reaction time (t.) and Rate are accumed from		
v	mi/hr 🔸	mi/hr 🔸	ft/sec ²	sec	2.2 chew/sec		ron pattern.	2	$d = v_o t + 1/2at^2$	ariables: <i>d</i> (i.	$ONLY EN t = (\sqrt{((v_o^2) + (2ad)) - v_o)/a}$			entering the	exiting the c			Esumare the deceleration rate (a).	nd Rate are		
8	55	45	-2.50	0.5	2.2	C OFI	the chev	equation:	$d = v_o t$	Known v	N t = (v(t))	W CELES.		he speed e	te speed e			me decele	hme (†) a	ure.	
A	Vo	Vf	e	tr	Rate	-	t total	Chev #	Spaces		ONLY E	VELLOW		Identify tl	(v_o) and the	(k).	F	Esumare	Reaction	the literature.	
	+	2	e	4	2	9	2	8	6	10	12	13	14	15	16	17	18	19	20	21	23

σ	Chev	Chevr	Chevr	Chevr	Chevr	Chevr	Then	evr	Ievr		BVT BVT	evre		R 1	Chevre						
LL.				Dire	ecti	on	0 10 Mac		- all wounds	number (i			in of the	<i>attern at 0</i> raffic Safet							
ш	15 ft/sec	5 ft/sec					C Enland Total number of chevrons needed to achieve the desired	ttern (v_r) .	Ac a concervative decion neverneter the cell wounds un	the number of chevrons to the next whole number (ie. a calcuation of 14.02 chevrons is rounded to 15 chevrone)	ONLY EN Accuración unilla ser el contrata de la contrat		Drakopoulos A., Vergou. G. 2003. Evaluation of the	Identify the Wisconsin Location. AAA Foundation for Traffic Safety.	rpmcm.				edfrom		
	80.85	66.15						hevron pa	acion nar	rons to th			gou. G. 20	AAA Foul	CHEVI OR			c (a).	re assim		
ပ	mi/hr →	mi/hr 🔸	-2.50 ft/sec ²	Sec	2.2 chev/sec	ft	mher of che	speed exiting the chevron pattern (v_r) .	convative d	ber of chev	m alaidan e		ulos A., Ver	in Location	(vo) and the speed coming means we mean			L stimate the deceleration rate (a) .	Reaction time (t_{*}) and Rate are assumed from		
8	55	45	-2.50	0.5	2.2	472.6 ft	Total nu	speed e	Ac a con	the num				De Wiscons	ie speed		-	the decele	time (t.) a	ure.	
A	Vo	Vf	e	tr	Rate	L	É total	Chev #	Spaces		ONLY F	VELLOW		Identify tl	(v_o) and the	(A)		Estimate	Reaction	the literature.	
	-	2	3	4	2	9	2	ω	6	10	12	13	14	15	16	17	18	19	20	21	23



INTEGRATED SPEED REDUCTION TREATEMENT FOR INTERSECTIONS

"GAP TIME CALCULATIONS"

4:00 - 4:15 pm
Volume = 305 verticles V= flow RATE
Average SPEED,
$$S = 41 \text{ mph}$$
 D= 0ENSITY
AVERAGE HERDOWRY, $h_a = 2.94$ sec
 $V = S \cdot D$
 $V = \frac{3,600}{h_a} = \frac{3,600}{2.94} = 1,224 \text{ veh}/hr/ln$
 $D = \frac{V'_S}{h_a} = \frac{1,224}{41} = 29.9 \text{ veh}/mi/ln$
Assume TREATMENT REDUCES AVERAGE SPEED
BY 5.0 mph. $S_2 = S_1 - 5 = 41 - 5 - 36 \text{ mph}$
 $V = S \cdot D = (36)(29.9) = 1076 \text{ veh}/hr/ln$
 $h_a = \frac{3,600}{V} = \frac{3,600}{1,076} = 3.35 \text{ sec}$
 $\Delta = h_{a_2} - h_{a_1} = 3.35 - 2.94 = 0.41 \text{ sec}$

B

5:00-5:15 pm Volume = 121 VENTICLES AVERAGE SPEED, S = 44 mph AVERAGE WEADWAY, ha = 7.38 sec

V= FLOW RATE D= DENSITY

$$V = \frac{3,600}{h_{a}} = \frac{3,600}{7.38} = 487 \text{ veh}/hr/ln$$

$$D = \frac{V}{S} = \frac{487}{44} = 11.1 \text{ veh}/mi/ln$$

Assume TREATMENT REDUCES AVERAGE SPEED BY 5.0 mph. $S_2 = S_1 - 5 = 44 - 5 = 39$ mph $V = S_2 \cdot D = (39)(11.1) = 433 \text{ veh}/hr/ln$ $h_a = \frac{3,600}{v} = \frac{3,600}{433} = 8.31$ sec $\Delta = h_{a_2} - h_{a_1} = 8.31 - 7.38 = 0.93$ sec **BENEFIT/COST ANALYSIS**

HS			Control Section	T.H./ Roadway		Location	1		1	Beginning Ref. Pt.	Ending Ref. Pt.	State, County, City or Township	Study Period Begins	Study Period Ends
			Descript Proposed	ion of d Work	Intersection of I	narrowin	g and conver	ging chevrons	s on			St. Louis Co.	1/1/2000	12/31/2009
Accide	ent Dia	gram Codes	1 Rear Ead		2 Sideswipe Same Direction	3 Left Tu	n Main Line	5 Right Angle	4,7	Rap off Read	8.9 Head On/ Sideswipe - Opposite Direction	Pedestrian	6, 90, 99 Other	Total
	(Pl) Fatal	F												
Study Period: Number of	Personal Injury	A B.					1	2	-				ì	3
Crashes	Property Pe	C		2			1	5						8
% Change	Patal D	PD F		5 54%	2			-42%		1	2		2	17
in Crashes	PI	A		54%				-42%						
"Lise Desktop Reference for Crash Reduction		B C		54% 54%				-42%				-		
Eactors	1. Property Damage	PD		54%				-42%						
	Fatal	F	<u></u>				0.00							
Change in Crashes	Ρl	B						-0.84					0.00	-0.84
= No. of crashes X % change in crashes	Property Dainage	C PD		1.08 2.70	0.00		0.00	-2.10 -2.10		0.00	0.00		0.00	-1.02
Year (Safety I	1	-	t Construc	-	2011		Study							
Project Cost	(exclu	de Ri	ght of Way	y)	\$ 25,000	Type of Crash	Period: Change in Crashes	Annual Change in Crashes		Cost per Crash	A nmual Benefit		B/C=	6.14
Right of Way Traffic Grow	_		tional)		2%	F A			<u>s</u>	780,000 390,000		Using present B=		s. 153,579
Capital Reco	very				4.5%	B	-0.84	-0.08	\$	121,000	\$ 10,158 \$ 7,646	C= See "Calculai amortization.	\$	25,000
2. Project !			le (n)		10	PD Total	0.60	0.06		12,000	\$ (720)	Office of Tra Technology		and aber 2008

	Crash	Present Worth	Present Worth
Year	Benefits	Benefits	Costs
2011	\$ 17,085 \$ 17,426 \$ 17,775 \$ 18,130 \$ 18,493 \$ 18,863 \$ 19,240 \$ 19,625 \$ 20,017 \$ 20,418 \$ - \$ - \$ - \$ - \$ - \$ - \$ - \$ - \$ - \$	\$ 17,085	\$ 25,000
2012	\$ 17,426	\$ 16,676	
2013	\$ 17,775	\$ 16,277	
2014	\$ 18,130	\$ 15,888	
2015	\$ 18,493	\$ 15,507	
2016	\$ 18,863	\$ 15,136	
2017	\$ 19,240	\$ 14,774	
2018	\$ 19,625	\$ 14,421	
2019	\$ 20,017	\$ 14,076	
2020	\$ 20,418	\$ 13,739	
0	\$ -	\$ -	
0	\$ -	\$-	
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0	\$ -	\$ -	
0	\$ -	\$ –	
0	\$ -	\$ -	
	Totals =	\$ 153,579 (B)	\$ 25,000 (C)

Amortizing...

year (n)= 1, 2, 3,.... discount rate (i) = 7%

> Crash Benefits (@ year n) = (Crash Benefits)_{n-1} X (1 + Traffic Growth Factor)

Present Worth Benefits (@ year n) = (Crash Benefits)_n $X 1/(1 + Discount Rate)^n$